

2. HAFOS: MAINTAINING THE AWI'S LONG-TERM OCEAN OBSERVATORY IN THE WEDDELL SEA

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Outline

The ocean is a key element of the global climate system due to its ability to store and transport large amounts of heat, to act as a sink of carbon dioxide, and due to the sea ice ocean albedo effect providing a positive feedback to sea ice melting. The response of the ocean to changes in the radiative and wind-driven forcing is controlled by its stratification as governed by the vertical structure of temperature and salinity. Until recently, ship-borne observations provided the only means to obtain sufficiently accurate vertical profiles of water mass properties. However, automated systems gained importance during the last decade. The current backbone of the oceanic observing system is Argo, an internationally financed and organized array of >3000 autonomous profiling floats with public, near-real time data access. However, Argo is by and large restricted to oceanic regions that are ice free year-round, as the floats need to surface regularly to be localized and to transmit their data. Furthermore, Argo does not access the deep ocean.

In an effort to overcome the observational constraints posed by high latitudes and the deep ocean, the Hybrid Antarctic Float Observing System (HAFOS) builds on vertically profiling, custom developed ice-resilient floats (Klatt et al. 2007) and a set of deep sea moorings deployed throughout the Weddell Gyre to record oceanographic data at selected sites. HAFOS also includes an ecological component using passive hydroacoustic recording devices embedded in each of the deep-sea moorings to collect data on the acoustic environment as shaped by manifold biotic and abiotic acoustic sources.

HAFOS was first established in its full extent in 2012/13 during *Polarstern* expedition ANT-29/2, yet subsets of the system existed in various configurations since 2002, allowing for the development and testing of components. The goal of this expedition is to service HAFOS by maintaining the mooring array to allow localizing ice-resilient floats deployed in 2018/19 and in preparation for the deployment of additional ice-resilient floats next year, and to recover and continue the deep temperature und salinity long-term time series monitoring the state of Antarctic Bottom Water.

Objectives

Being the physical oceanography core project of this expedition, HAFOS intends to investigate the role of the Southern Ocean in the global climate system with focus on the Atlantic sector, including the Weddell Sea, where the densest bottom waters of the global oceans originate

(Behrendt et al. 2011; Fahrbach et al. 2011; Fahrbach et al. 2007). The production of these dense water is controlled by the balance between:

- supplies of fresh water through precipitation,
- the melting of continental and sea ice,
- the extraction of freshwater by sea ice formation and evaporation, and
- a supply of warm and salty water masses as transported by the subpolar gyres towards the continental margins of Antarctica, with the gyres of the Weddell and Ross Seas being their most prominent expressions.

The basic mechanism of dense water generation involves upwelling of Circumpolar Deep Water (CDW), which is relatively warm and salty, into the surface layer where CDW comes into contact with the atmosphere and sea ice, becoming cooled and freshened. The newly formed bottom water formed hereby is significantly colder and slightly fresher than the initial Circumpolar Deep Water, which indicates heat loss and the addition of freshwater. Since freshwater input in the upper oceanic layers would impede sinking due to increasing stratification of the water column, it has to be compensated by salt gain through freshwater extraction. Significant parts of salt accumulation occur on the Antarctic shelves in coastal polynyas. With extreme heat losses occurring over ice-free water areas, the polynyas are areas of intense sea ice formation. Offshore winds compress the newly formed sea ice and keep an open sea surface in the polynyas.

The properties and volume of the newly formed bottom water are subject to significant variability on a wide range of time scales, which can only scarcely be explored due to the large efforts needed to obtain measurements in ice-covered ocean areas. Seasonal variations of the upper ocean layers are only partially known and normally exceed other scales of variability in intensity. Impacts of longer-term variations of the atmosphere-ice-ocean system, such as the Southern Hemispheric Annular Mode and the Antarctic Dipole, are only poorly monitored and understood. Their influence on or interaction with oceanic conditions are merely guessed on the basis of models, which are only superficially validated due to lack of appropriate measurements.

This extreme regional and temporal variability represents a large source of uncertainty when data sets of different origin are combined. Therefore, circumpolar data sets of sufficient spatial and temporal coverage are required and until recently could only be acquired for surface or integral properties by satellite remote sensing. However, to penetrate into the ocean interior and validate the remotely sensed data, an ocean observing system is required, which combines remotely sensed data of sea ice and surface properties with long-term *in-situ* measurements of ocean interior properties, i.e., HAFOS.

Work at sea

The oceanographic studies during *Polarstern* expedition PS129 will concentrate on two major areas, the Greenwich Meridian and the Weddell Sea, continuing more than 30 years of *in-situ* observations in the Atlantic sector of the Southern Ocean. Employing moored instruments, we seek to obtain time series of water mass properties throughout the deep and the surface layers. For this purpose, moorings featuring current meters, temperature and salinity sensors, sound sources and passive acoustic recorders, will be recovered and redeployed (Tables 2.1 and 2.2). While, during the previous expeditions ANT-29/2, ANT-30/2 (PS89), PS103 and PS117, the recovery of moorings in ice-covered areas was facilitated significantly using the ultra-short line positioning system (POSEIDONIA), it nevertheless was not possible to retrieve some moorings due to the ice conditions. For this reason, a ROV has been acquired and developed to recover moorings directly by hooking a recovery rope to the mooring rope.

Tab. 2.1: Scientific instrumentation of planned moorings recoveries during PS129

Mooring	Latitude Longitude	Decimal Lat Decimal Lon	Water Depth [m]	Date Time	Instrument Type	Instrument S/N	Instrument Depth [m]
AWI 227-15	59° 03.02' S	-59.0503	4648	31.12.2018	PAM	1006	300
	00° 06.44' E	0.1073		10:10	SBE37	12479	4597
AWI 229-14	64° 01.26' S	-64.0210	5193	01.01.2019	SBE37	9494	50
	00° 00.83' E	0.0138		22:38	SBE37	9495	100
					SBE37	9496	150
					SBE37	9497	200
					AquaD	12654	230
					SBE37	9492	231
					PAM	1060	300
					SBE37	2098	330
					SBE37	2385	430
					SBE37	2382	530
					SBE37	2396	630
					SBE37	3811	734
					AquaD	12658	735
					SBE37	12481	5152
AWI 231-13	66° 31.03' S	-66.5172	4612	27.12.2018	PAM	1056	300
	00° 04.48' W	-0.0747		18:34	SBE37	10944	4534
AWI 244-6	69° 00.08' S	-69.0013	2984	05.01.2019	PAM	1049	300
	07° 01.65' W	-7.0275		20:01	SBE37	8122	2903
AWI 248-3	65° 58.12' S	-65.9687	5048	07.01.2019	PAM	1012	300
	12° 13.84' W	-12.2307		10:37	SBE37	8123	5003
AWI 245-5	69° 03.64' S	-69.0607	4773	08.01.2019	PAM	1014	300
	17° 23.49' W	-17.3915		14:20	SBE37	8124	4693
BGC-1	69° 00.07' S	-69.0012	4717	24.03.2021	LOC	NaN	40
	27° 00.07' W	-27.0012		13:14	ISUS	NaN	40
					CO2	219	40
					RAS-500	12073	40
					Ecotriplet	17c	40
					SBE37	21026	40
					ADCP WH	12667	40
					SBE 56	7824	60
					SBE 37	2100	80

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Mooring	Latitude Longitude	Decimal Lat Decimal Lon	Water Depth [m]	Date Time	Instrument Type	Instrument S/N	Instrument Depth [m]
					SBE 56	7825	120
					SBE 37	386	147
					Octopus	NA	156
					Suna	1122	156
					Vp6	7LP	156
					SBE 56	6513	158
					Sedimenttrap	2009404	511
					SonoVault	1024	918
					Sedimenttrap	2009406	1525
AWI 249-3	70° 53.22' S	-70.8870	4407	20.01.2019	PAM	1010	300
	28° 56.97' W	-28.9495		12:00	SBE37	8126	4357
AWI 208-9	65° 41.78' S	-65.6963	4766	23.01.2019	PAM	1020	300
	36° 41.01' W	-36.6835		16:01	AquaD	12685	806
					SBE37	3812	807
					SBE37	9841	4758
AWI 250-3	68° 28.85' S	-68.4808	4141	24.01.2019	PAM	1048	300
	44° 05.94' W	-44.0990		20:28	AquaD	12718	819
					SBE37	3813	820
					SBE37	9839	4094
AWI 257-2	64° 12.94' S	-64.2157	4215	27.01.2019	PAM	1033	3001
	47° 29.38' W	-47.4897		17:50	RCM	11888	813
					SBE37	10944	814
					SBE37	9493	4285
AWI 207-11	63° 39.36' S	-63.6560	2555	29.01.2019	SBE37	10934	250
	50° 48.66' W	-50.8110		17:08	ADCP QM150	23548	291
					PAM	1032	300
					AquaD	12745	802
					SBE37	6928	803
					SBE37	10937	2200
					AVT	3517	2248
					SBE39	8641	2259
					SBE39	8642	2305

Mooring	Latitude Longitude	Decimal Lat Decimal Lon	Water Depth [m]	Date Time	Instrument Type	Instrument S/N	Instrument Depth [m]
					SBE39	8643	2355
					SBE37	10943	2406
					ADCP QM150	24053	2545
					SBE37	9847	2545
AWI 251-3	61° 01.38' S	-61.0230	335	01.02.2019	PAM	AU0085	179
	55° 58.68' W	-55.9780		18:30	PAM	1002	181
					AZFP	55037	288
					ADCP QM150	5373	322
					SBE37	2096	322

Tab. 2.2: Scientific instrumentation of planned mooring deployments during PS129

Mooring	Latitude Longitude	Decimal Lat Decimal Long	Water Depth [m]	Date Time	Instrument Type	Instrument S/N	Instrument Depth [m]
AWI 227-16	59° 03.02' S	-59.0503	4648		SonoVault		300
	00° 06.44' E	0.1073			SBE37	10933	800
					SBE37	...	4562
AWI 229-15	64° 01.26' S	-64.0210	5193		SBE37	10929	256
	00° 00.83' E	0.0138			SonoVault	...	300
					SBE37	10930	355
					SBE37	2092	455
					SBE37	10931	555
					SBE37	2093	655
					SBE37	10932	755
					SBE37	...	5016
AWI 231-14	66° 31.03' S	-66.5172	4612		SonoVault	...	300
	00° 04.48' W	-0.0747			SBE37	9848	800
					SBE37	...	4536
EWS 001-01	70° 47.87' S	-70.7978			SBE 37	7729	19
	12° 13.05' W	-12.2175			SBE56	...	150
					SBE56	...	300
					ADCP QM150	23807	341

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Mooring	Latitude	Decimal Lat	Water Depth [m]	Date Time	Instrument Type	Instrument S/N	Instrument Depth [m]
	Longitude	Decimal Long					
					SBE 37	7730	346
					SBE56	...	400
					SBE56	...	460
					SBE 37	7731	520
					SBE56	...	580
					ADCP WH600	1002	652
					SBE56	...	652
					SBE 37	10928	693
EWS 002-01	70° 35.17' S	-70.5861			SBE 37	7733	18
	12° 51.46' W	-12.8576			SBE56	...	100
					SBE56	...	200
					ADCP QM150	22283	341
					SBE 37	8122	346
					SBE56	...	500
					SBE56	...	600
					SBE56	...	700
					SBE 37	9490	800
					SBE56	...	900
					SBE56	...	1000
					SBE 37	10949	1100
					SBE56	...	1200
					ADCP WH300	951	1302
					SBE 37	...	1393
EWS 003-01		-70.3464			SonoVault	...	290
		-13.5746			SoSo	...	794
					Aquadopp	...	795
					SBE 37	3814	795
					SBE 37	224	2959
AWI 245-06	69° 03.64' S	-69.0607	4773		SonoVault	...	300
	17° 23.49' W	-17.3915			SoSo	...	841
					Aquadopp	...	841
					SBE37	9838	841
					SBE37	218	4691

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Mooring	Latitude Longitude	Decimal Lat Decimal Long	Water Depth [m]	Date Time	Instrument Type	Instrument S/N	Instrument Depth [m]
AWI 249-04	70° 53.22' S 28° 56.97' W	-70.8870 -28.9495	4407		SonoVault SoSo Aquadopp SBE37 SBE37 9832 ...	300 809 809 809 4319
CWS 001-01	69° 57.55' S 36° 43.87' W	-69.9592 -36.7312	4243		Aural SonoVault SoSo AquaD SBE37 SBE37		291 293 795 819 7727 797
AWI 209-09	66° 36.45' S 27° 07.29'W	-66.6075 -27.1215			SonoVault SoSo AquaD SBE37 SBE37 9832 ...	300 809 809 809 4319
AWI 208-10	65° 41.78' S 36° 41.01' W	-65.6963 -36.6835	4766		PAM AquaD SBE37 SBE37		300 806 807 4758
AWI 250-04	68° 28.85' S 44° 05.94' W	-68.4808 -44.0990	4141		PAM SoSo AquaD SBE37 SBE37		294 795 797 2101 4057
WWS 002-01	66° 34.62' S 44° 00.91' W	-66.5770 -50.0152	3517		Aural SonoVault SoSo AquaD SBE37 SBE37		291 293 792 795 9488 795
AWI 257-03	64° 12.94' S 47° 29.38' W	-64.2157 -47.4897	4215		PAM SoSo AquaD SBE37		311 811 11330 811
					SBE37	7690	811

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Mooring	Latitude	Decimal Lat	Water Depth [m]	Date Time	Instrument Type	Instrument S/N	Instrument Depth [m]
	Longitude	Decimal Long			SBE37		4279
AWI 207-12	63° 39.36' S	-63.6560	2555	29.01.2019	SM37	8131	249
	50° 48.66' W	-50.8110		17:08	QM150	23456	290
					SonoVault		300
					SM37	10951	805
					SM37	8129	2200
					AquaD	11348	2203
					SBE39		2210
					SBE39		2260
					SBE39		2310
					SBE39	8643	2355
					SM37	2234	2410
					QM150	24052	2500
					SBE37	2009	2500
AWI 261-02	63° 30.87' S	-63.5145	1726		PAM		290
	50° 38.20' W	-51.6367			SBE37	9840	790
					SBE56		1150
					SBE37	2092	1200
					SBE56		1250
					SBE37	2093	1291
					SBE56		1350
					SBE37	9834	1400
					SBE56		1450
					SBE37	12478	1491
					ADCP QM150	14088	1491
AWI 251-04	61° 01.38' S	-61.0230	335		PAM		179
	55° 58.68' W	-55.9780			PAM		181
					AZFP		288
					ADCP LR 075	22858	322
					SBE37	2395	322

Abbreviations:

<i>ADCP LR075</i>	<i>RD Instruments Doppler Current Profiler, Type Long Ranger 75 kHz</i>
<i>ADCP QM150</i>	<i>RD Instruments Doppler Current Profiler, Type Quarter Master 150 kHz</i>
<i>ADCP WH600</i>	<i>RD Instruments Doppler Current Profiler, Type Workhorse 600 kHz</i>
<i>AquaD</i>	<i>Nortek Aquadopp Acoustic Current Meter</i>
<i>Aural</i>	<i>Multi-Electronique (MTE) Aural Passive Acoustic Recorder</i>
<i>AVT</i>	<i>Aanderaa Current Meter with Temperature Sensor</i>
<i>AZFP</i>	<i>ASL Environmental Sciences Acoustic Zooplankton and Fish Profiler</i>
<i>PAM</i>	<i>Passive Acoustic Monitor (Type: AURAL or SONOVAULT)</i>
<i>RCM11</i>	<i>Aanderaa Doppler Current Meter (acoust.)</i>
<i>SBE37</i>	<i>SeaBird Electronics MicroCat Conductivity and Temperature Logger</i>
<i>SBE39</i>	<i>SeaBird Electronics Temperature Logger</i>
<i>SBE56</i>	<i>SeaBird Electronics Temperature Logger</i>
<i>SonoVault</i>	<i>Develogic SonoVault Passive Acoustic Recorder</i>
<i>SOSO</i>	<i>Develogic RAFOS Sound Source</i>

Ecotriplet Fluorescence sensor

ISUS *Nitrate Sensor*

LOC *Lab on Chip sensors*

RAS-500 Remote Access Sampler RAS-48-500

Sedimenttrap *KUM sediment traps*

Suna *Nitrate Sensor*

VVP6 *Underwater Vision Profiler 6*

To enhance the vertical resolution and to calibrate moored sensors, CTD stations will be occupied at the mooring locations. The CTD/water sampler consists of a SBE911plus CTD system in combination with a carousel water sampler SBE32 with 24 12L bottles. To determine the distance to the bottom, an altimeter from Bentho is mounted. A transmissometer from Wetlabs, a SBE43 oxygen sensor from Seabird Electronics and a fluorometer will be incorporated in the sensor package. Additionally, two RDI-150 kHz ADCPs, one pointing upward, one pointing downward are attached to the rosette sampler to measure the current velocity profile.

Moorings will contain sound sources, providing RAFOS signals for retrospective under-ice tracking of 23 NEMO floats deployed during PS129 (Table 2.3, Fig. 2.2) and passive acoustic recorders to record ambient (biotic and abiotic) sounds. During PS129, 5 Argo floats will be deployed for the Bundesamt für Seeschifffahrt und Hydrographie (BSH, Table 2.4) across the ACC throughout the Weddell Sea. Further 9 biogeochemical Argo floats shall be deployed for Scripps Institution of Oceanography (Table 2.5). A CTD/I-ADCP section shall be conducted between mooring 217-5 (near 45° E) and the tip of the Antarctic Peninsula (Fig. 2.1) aiming at delineating the export plume of Antarctic Bottom Water.

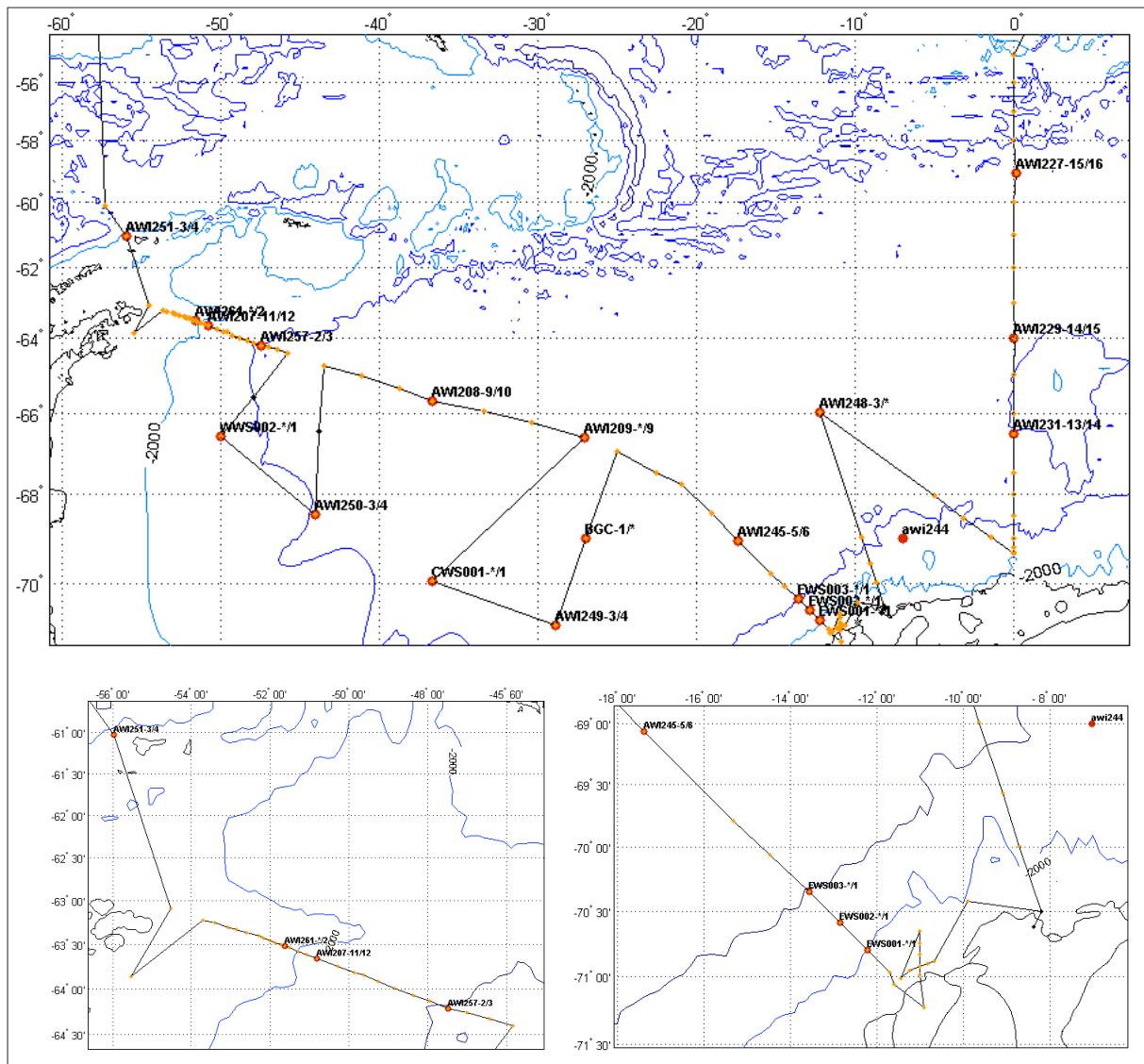


Fig. 2.1: Overview (top) and zoomed-in (bottom left: Antarctic Peninsula; bottom right: Kapp Norvegia) charts of the study area with planned expedition track. Red circles with labels: Locations and names of oceanographic moorings to be recovered (labels featuring numerals preceding slash) and redeployed (labels featuring numerals following slash). Orange dots: Locations of planned stations

Tab. 2.3: List of planned ice-resilient Argo float deployments during PS129. All floats are of type APEX by Teledyne Webb Research and their planned deployments have been registered with www.ocean-ops.org.

AWI-ID	Apex float S/N	WMO	IMEI	Deployment latitude	Deployment longitude	Water depth [m]
PS129-1	8878	7900971	300125061811150	68° 00.00' S	0° 00.00' E	4522
PS129-2	8879	7900972	300125061814250	69° 00.00' S	0° 00.00' E	3421
PS129-3	8886	7900979	300125061326710	69° 21.84' S	0° 00.00' E	2303
PS129-4	8887	7900980	300125061324710	68° 59.75' S	1° 27.67' W	3031

AWI-ID	Apex float S/N	WMO	IMEI	Deployment latitude	Deployment longitude	Water depth [m]
PS129-5	8888	7900981	300125061323740	68° 32.69' S	3° 10.23' W	4087
PS129-6	8889	7900982	300125061326720	68° 02.47' S	5° 01.47' W	4421
PS129-7	8890	7900983	300125061321650	68° 59.12' S	9° 37.84' W	4297
PS129-8	8891	7900984	300125061321740	69° 34.18' S	9° 04.82' W	3397
PS129-9	8892	7900985	300125061810140	69° 59.33' S	8° 42.40' W	2855
PS129-10	8893	7900986	300125061813240	70° 25.19' S	9° 53.30' W	1696
PS129-11	9212	7900987	300125061140800	70° 57.93' S	11° 42.32' W	752
PS129-12	9213	7900988	300125061142720	70° 47.87' S	12° 13.05' W	1810
PS129-13	9214	7900989	300125061756090	70° 35.17' S	12° 51.46' W	2198
PS129-14	9215	7900990	300125061143710	70° 20.78' S	13° 34.48' W	3234
PS129-15	9216	7900991	300125061163760	70° 03.61' S	14° 28.25' W	4755
PS129-16	9217	7900992	300125061246210	69° 47.26' S	15° 20.49' W	4755
PS129-17	9218	7900993	300125061165760	69° 03.64' S	17° 23.49' W	4774
PS129-18	9219	7900994	300125061148800	70° 53.22' S	28° 56.97' W	4367
PS129-19	9220	7900995	300125061144830	70° 53.22' S	28° 56.97' W	4367
PS129-20	9221	7900996	300125061167760	69° 57.55' S	36° 43.87' W	4243
PS129-21	9222	7900997	300125061163750	69° 57.55' S	36° 43.87' W	4243
PS129-22	9223	7900998	300125061162770	68° 28.85' S	44° 05.94' W	4081
PS129-23	9224	7900999	300125061162760	66° 34.62' S	50° 00.91' W	3517

Table 2.4: List of planned standard Argo float deployments during PS129. All floats provided by BSH.

BSH-ID	Apex float S/N	WMO	IMEI	Deployment latitude	Deployment longitude	
PS129-BSH1				45° 0' S	10° 30.00' E	
PS129-BSH2				47° 0' S	9° 00.00' E	
PS129-BSH3				50° 0' S	6° 30.00' E	
PS129-BSH4				58° 30.00' S	0° 30.00' E	
PS129-BSH5				59° 30.00' S	0° 00.00' E	

Tab. 2.5: List of planned biogeochemical Argo float deployments during PS129. All floats provided by Scripps Institution of Oceanography.

Scripps ID	float S/N	WMO	IMEI	Deployment latitude	Deployment longitude	Water depth [m]
				-37.5000	14.9200	
				-40.5000	13.3000	
				-62.0000	0.0000	
				-65.0006	0.0237	
				-69.0057	-6.9823	
				-65.9682	-12.2520	
				-66.6075	-27.1210	
				-65.6205	-36.4220	
				-64.3321	-46.4369	

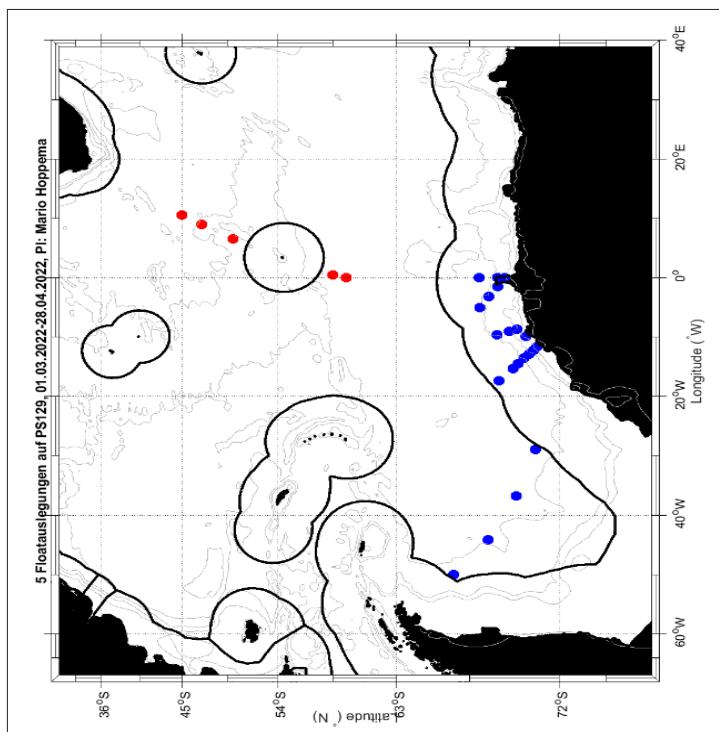


Fig. 2.4: Map of deployment sites for ice-resilient (blue) and standard (red) Argo floats during PS129. Graphics courtesy of Birgit Klein, BSH

Expected results

We expect to secure data from a large proportion of the instruments currently moored, together with ship-based CTD- and lowered ADCP data.

Data management

Environmental data will be archived, published and disseminated according to international standards by the World Data Center PANGAEA Data Publisher for Earth & Environmental Science (<https://www.pangaea.de>) within two years after the end of the cruise at the latest. By default, the CC-BY license will be applied.

Metadata of recoded data will be made available through the expedition report. Mooring and CTD data will be made available after validation through the PANGAEA database. Float data will be made available through the Argo System and PANGAEA (Reeve et al., 2016). The processing of the lowered ADCP will last several months but as soon as these data were processed and documented they will be available in PANGAEA too. Results will be published in international journals.

In all publications, based on this cruise, the grant no. AWI_PS129_00 will be quoted and the following *Polarstern* article will be cited:

Alfred-Wegener-Institut Helmholtz-Zentrum für Polar- und Meeresforschung (2017) Polar Research and Supply Vessel POLARSTERN Operated by the Alfred-Wegener-Institute. Journal of large-scale research facilities, 3, A119. <http://dx.doi.org/10.17815/jlsrf-3-163>.

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Appendix 1

Current planning of stations to be occupied during PS129

Station	Cast	Latitude	Longitude	Water Depth [m]	Instrument	Comment
WP	none	-32.699	17.9331	22	Cape Town(sf)	
1	1	-55	0	2008	CTD/RO	
2	1	-56	0	3597	CTD/RO	
3	1	-57	0	3852	CTD/RO	
4	1	-58	0	4010	CTD/RO	
5	1	-59.0503	0.1073	4777	MOOR/R	Recovery AWI227-15
5	2	-59.0503	0.1073	4777	CTD/RO	Attention keep 2 nm off mooring
5	3	-59.0503	0.1073	4777	MOOR/D	Deployment AWI227-16
6	1	-60	0	5149	CTD/RO	
6	2	-60	0	5149	MN	
6	3	-60	0	5149	RMT	
6	4	-60	0	5149	ICAM	
7	1	-61	0	5437	CTD/RO	
8	1	-62	0	5177	CTD/RO	
8	2	-62	0	5177	MN	
8	3	-62	0	5177	RMT	
8	4	-62	0	5177	ICAM	
9	1	-63	0	5293	CTD/RO	
10	1	-64.021	0.0138	5056	MOOR/R	Recovery AWI229-14
10	2	-64.021	0.0138	5056	CTD/RO	Attention keep 2 nm off mooring
10	3	-64.021	0.0138	5056	MOOR/D	Deployment AWI229-15
11	1	-65	0	3856	CTD/RO	
11	2	-65	0	3856	MN	
11	3	-65	0	3856	RMT	
11	4	-65	0	3856	ICAM	
12	1	-66	0	3490	CTD/RO	
12	2	-66	0	3490	MN	
12	3	-66	0	3490	RMT	
12	4	-66	0	3490	ICAM	
12	5	-66	0	3490	TRAPS	
13	1	-66.5172	-0.0747	4543	MOOR/R	Recovery AWI231-13
13	2	-66.5172	-0.0747	4543	CTD/RO	Attention keep 2 nm off mooring
13	3	-66.5172	-0.0747	4543	MOOR/D	Deployment AWI231-14
14	1	-67.5	0	4667	CTD/RO	
15	1	-68	0	4522	CTD/RO	

Station	Cast	Latitude	Longitude	Water Depth [m]	Instrument	Comment
15	2	-68	0	4522	FLOAT	
16	1	-68.5	0	4255	CTD/RO	
17	1	-69	0	3421	CTD/RO	
17	2	-69	0	3421	FLOAT	
18	1	-69.224	0	2784	CTD/RO	
18	2	-69.224	0	2784	SUIT	
18	3	-69.224	0	2784	MN	
18	4	-69.224	0	2784	RMT	
18	5	-69.224	0	2784	ICE	
18	6	-69.224	0	2784	ICAM	
19	1	-69.329	0	2437	CTD/RO	
20	1	-69.364	0	2303	CTD/RO	
20	2	-69.364	0	2303	FLOAT	
21	1	-68.9958	-1.4612	3031	FLOAT	
22	1	-68.5448	-3.1705	4087	FLOAT	
23	1	-68.0412	-5.0245	4421	FLOAT	
24	1	-65.9687	-12.2307	5022	MOOR/R	Recovery AWI248-3
24	2	-65.9687	-12.2307	5022	CTD/RO	Attention keep 2 nm off mooring
25	1	-68.9854	-9.6307	4297	FLOAT	
26	1	-69.5697	-9.0803	3397	FLOAT	
27	1	-69.9888	-8.7067	2855	FLOAT	
WP	none	-70.504	-8.2	258	waypoint	
WP	none	-70.6166	-8.3666	282	Neumayer arrival	
WP	none	-70.6166	-8.3666	282	Neumayer departure	
WP	none	-70.504	-8.2	258	waypoint	
28	1	-70.4198	-9.8883	1696	FLOAT	
29	1	-70.883	-10.663	281	SUIT	
29	2	-70.883	-10.663	281	MN	
29	3	-70.883	-10.663	281	RMT	
29	4	-70.883	-10.663	281	ICE	
29	5	-70.883	-10.663	281	ICAM	
29	6	-70.883	-10.663	281	TRAPS	
29	7	-70.883	-10.663	281	ROV	
29	8	-70.883	-10.663	281	TVMUC	
29	9	-70.883	-10.663	281	TVMUC	
29	10	-70.883	-10.663	281	MG	
29	11	-70.883	-10.663	281	OFOS	
30	1	-70.9	-10.835	308	LANDER	
30	2	-70.9	-10.835	308	MG	

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Station	Cast	Latitude	Longitude	Water Depth [m]	Instrument	Comment
30	3	-70.9	-10.835	308	OFOS	
31	1	-70.921	-11.016	360	SUIT	
31	2	-70.921	-11.016	360	MN	
31	3	-70.921	-11.016	360	RMT	
31	4	-70.921	-11.016	360	ICE	
31	5	-70.921	-11.016	360	ROV	
31	6	-70.921	-11.016	360	LANDER	
31	7	-70.921	-11.016	360	TVMUC	
31	8	-70.921	-11.016	360	TVMUC	
31	9	-70.921	-11.016	360	MG	
31	10	-70.921	-11.016	360	OFOS	
32	1	-70.954	-11.247	357	LANDER	
32	2	-70.954	-11.247	357	TVMUC	
32	3	-70.954	-11.247	357	MG	
32	4	-70.954	-11.247	357	OFOS	
33	1	-71.009	-11.435	433	LANDER	
33	2	-71.009	-11.435	433	TVMUC	
33	3	-71.009	-11.435	433	MG	
33	4	-71.009	-11.435	433	OFOS	
34	1	-70.651	-11	1432	AGT	
34	2	-70.651	-11	1432	AGT	
34	3	-70.651	-11	1432	LL	
34	4	-70.651	-11	1432	LL	
35	1	-70.743	-11	1133	LANDER	
35	2	-70.743	-11	1133	AGT	
35	3	-70.743	-11	1133	AGT	
35	4	-70.743	-11	1133	LL	
35	5	-70.743	-11	1133	LL	
35	6	-70.743	-11	1133	TVMUC	
35	7	-70.743	-11	1133	MG	
35	8	-70.743	-11	1133	OFOS	
36	1	-70.831	-11	474	SUIT	
36	2	-70.831	-11	474	MN	
36	3	-70.831	-11	474	RMT	
36	4	-70.831	-11	474	ICE	
36	5	-70.831	-11	474	ICAM	
36	6	-70.831	-11	474	TRAPS	
36	7	-70.831	-11	474	ROV	
36	8	-70.831	-11	474	LANDER	
36	9	-70.831	-11	474	AGT	

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Station	Cast	Latitude	Longitude	Water Depth [m]	Instrument	Comment
36	10	-70.831	-11	474	AGT	
36	11	-70.831	-11	474	LL	
36	12	-70.831	-11	474	LL	
36	13	-70.831	-11	474	TVMUC	
36	14	-70.831	-11	474	MG	
36	15	-70.831	-11	474	OFOS	
37	1	-70.988	-11	377	LANDER	
37	2	-70.988	-11	377	TVMUC	
37	3	-70.988	-11	377	MG	
37	4	-70.988	-11	377	OFOS	
38	1	-71.2307	-10.9097	606	MOOR/D	
38	2	-71.2307	-10.9097	606	CTD/RO	
39	1	-71.056	-11.597	344	SUIT	
39	2	-71.056	-11.597	344	MN	
39	3	-71.056	-11.597	344	RMT	
39	4	-71.056	-11.597	344	ICE	
39	5	-71.056	-11.597	344	ICAM	
39	6	-71.056	-11.597	344	TRAPS	
39	7	-71.056	-11.597	344	ROV	
39	8	-71.056	-11.597	344	LANDER	
39	9	-71.056	-11.597	344	TVMUC	
39	10	-71.056	-11.597	344	TVMUC	
39	11	-71.056	-11.597	344	MG	
39	12	-71.056	-11.597	344	OFOS	
40	1	-70.9655	-11.7053	752	MOOR/D	
40	2	-70.9655	-11.7053	752	CTD/RO	
40	3	-70.9655	-11.7053	752	FLOAT	
41	1	-70.7978	-12.2175	1810	MOOR/D	EWS001-1 Deploy
41	2	-70.7978	-12.2175	1810	CTD/RO	
41	3	-70.7978	-12.2175	1810	FLOAT	
42	1	-70.5861	-12.8576	2198	MOOR/D	EWS002-1 Deploy
42	2	-70.5861	-12.8576	2198	CTD/RO	
42	3	-70.5861	-12.8576	2198	FLOAT	
43	1	-70.3464	-13.5746	3234	MOOR/D	EWS003-1 Deploy
43	2	-70.3464	-13.5746	3234	CTD/RO	
43	3	-70.3464	-13.5746	3234	FLOAT	
44	1	-70.0602	-14.4709	4755	CTD/RO	
44	2	-70.0602	-14.4709	4755	FLOAT	
45	1	-69.7877	-15.3415	4755	CTD/RO	
45	2	-69.7877	-15.3415	4755	FLOAT	

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Station	Cast	Latitude	Longitude	Water Depth [m]	Instrument	Comment
46	1	-69.0607	-17.3915	4774	MOOR/R	Recovery AWI245-5
46	2	-69.0607	-17.3915	4774	CTD/RO	Attention keep 2 nm off mooring
46	3	-69.0607	-17.3915	4774	MOOR/D	Deployment AWI245-6
46	4	-69.0607	-17.3915	4774	FLOAT	
47	1	-68.4464	-19.0801	4839	CTD/RO	
48	1	-67.7429	-20.9806	4915	CTD/RO	
49	1	-67.476	-22.5503	4907	CTD/RO	
50	1	-66.9705	-25.0575	4876	CTD/RO	
50	2	-66.9705	-25.0575	4876	MN	
50	3	-66.9705	-25.0575	4876	RMT	
50	4	-66.9705	-25.0575	4876	ICAM	
50	5	-66.9705	-25.0575	4876	TRAPS	
51	1	-69.0012	-27.0012	4708	MOOR/R	BGC-1 Recovery
51	2	-69.0012	-27.0012	4708	CTD/RO	
52	1	-70.887	-28.9495	4367	MOOR/R	Recovery AWI249-3
52	2	-70.887	-28.9495	4367	CTD/RO	Attention keep 2 nm off mooring
52	3	-70.887	-28.9495	4367	MOOR/D	Deployment AWI249-4
52	4	-70.887	-28.9495	4367	SUIT	
52	5	-70.887	-28.9495	4367	ICE	
52	6	-70.887	-28.9495	4367	FLOAT	
52	7	-70.887	-28.9495	4367	FLOAT	
53	1	-69.9592	-36.7312	4243	CTD/RO	
53	2	-69.9592	-36.7312	4243	MOOR/D	Deploy CWS001-1
53	3	-69.9592	-36.7312	4243	SUIT	
53	4	-69.9592	-36.7312	4243	ICE	
53	5	-69.9592	-36.7312	4243	FLOAT	
53	6	-69.9592	-36.7312	4243	FLOAT	
54	1	-66.6075	-27.1215	4844	MOOR/D	Deployment AWI209-9
54	2	-66.6075	-27.1215	4844	CTD/RO	Attention keep 2 nm off mooring
55	1	-66.2488	-30.435	4823	CTD/RO	
56	1	-65.9374	-33.4566	4800	CTD/RO	
57	1	-65.6963	-36.6835	4701	MOOR/R	Recovery AWI208-9
57	2	-65.6963	-36.6835	4701	CTD/RO	Attention keep 2 nm off mooring
57	3	-65.6963	-36.6835	4701	MOOR/D	Deployment AWI208-10
58	1	-65.3545	-38.7161	4723	CTD/RO	
59	1	-65.0407	-41.1417	4716	CTD/RO	
60	1	-64.7425	-43.522	4600	CTD/RO	

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Station	Cast	Latitude	Longitude	Water Depth [m]	Instrument	Comment
WP	none	-66.4528	-43.8719	4295	waypoint	
61	1	-68.4808	-44.099	4081	MOOR/R	Recovery AWI250-3
61	2	-68.4808	-44.099	4081	CTD/RO	Attention keep 2 nm off mooring
61	3	-68.4808	-44.099	4081	MOOR/D	Deployment AWI250-4
61	4	-68.4808	-44.099	4081	ICE	
61	5	-68.4808	-44.099	4081	SUIT	
61	6	-68.4808	-44.099	4081	SOSOCAL	
61	7	-68.4808	-44.099	4081	SOSOCAL	
61	8	-68.4808	-44.099	4081	FLOAT	
62	1	-66.577	-50.0152	3517	MOOR/D	
62	2	-66.577	-50.0152	3517	SOSOCAL	
62	3	-66.577	-50.0152	3517	SOSOCAL	
62	4	-66.577	-50.0152	3517	FLOAT	
WP	none	-65.5845	-47.9297	3987	waypoint	
63	1	-64.4098	-45.8455	4400	CTD/RO	
63	2	-64.4098	-45.8455	4400	SUIT	
63	3	-64.4098	-45.8455	4400	MN	
63	4	-64.4098	-45.8455	4400	RMT	
63	5	-64.4098	-45.8455	4400	ICE	
64	1	-64.3321	-46.4369	4400	CTD/RO	
65	1	-64.2574	-47.0054	4289	CTD/RO	
66	1	-64.2157	-47.4897	4171	MOOR/R	Recovery AWI257-2
66	2	-64.2157	-47.4897	4171	CTD/RO	Attention keep 2 nm off mooring
66	3	-64.2157	-47.4897	4171	MOOR/D	Deployment AWI257-3
67	1	-64.1342	-47.9651	4082	CTD/RO	
68	1	-64.0665	-48.3813	3926	CTD/RO	
69	1	-63.9874	-48.8512	3675	CTD/RO	
70	1	-63.9173	-49.2678	3407	CTD/RO	
71	1	-63.8471	-49.6199	3161	CTD/RO	
72	1	-63.816	-49.8579	2984	CTD/RO	
73	1	-63.7427	-50.2799	2600	CTD/RO	
74	1	-63.656	-50.811	2494	MOOR/R	Recovery AWI207-11
74	2	-63.656	-50.811	2494	CTD/RO	Attention keep 2 nm off mooring
74	3	-63.656	-50.811	2494	MOOR/D	Deployment AWI207-12
75	1	-63.6163	-51.0719	2320	CTD/RO	
76	1	-63.58	-51.2986	2165	CTD/RO	
77	1	-63.5395	-51.5014	1993	CTD/RO	

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Station	Cast	Latitude	Longitude	Water Depth [m]	Instrument	Comment
78	1	-63.5148	-51.6367	1730	CTD/RO	
78	2	-63.5148	-51.6367	1730	MOOR/D	Deployment AWI261-2
79	1	-63.4972	-51.7338	1453	CTD/RO	
80	1	-63.4783	-51.8732	1210	CTD/RO	
81	1	-63.4527	-51.9968	1016	CTD/RO	
82	1	-63.4283	-52.1555	882	CTD/RO	
83	1	-63.4033	-52.2868	678	CTD/RO	
84	1	-63.3654	-52.5998	500	CTD/RO	
85	1	-63.3349	-52.8537	457	CTD/RO	
86	1	-63.3064	-53.0668	424	CTD/RO	
87	1	-63.2553	-53.4056	400	CTD/RO	
88	1	-63.22	-53.7067	332	CTD/RO	
88	2	-63.22	-53.7067	332	MOOR/D	
89	1	-63.862	-55.5333	298	TVMUC	
90	1	-63.0882	-54.5248	405	CTD/RO	
91	1	-61.023	-55.978	264	MOOR/R	Recovery AWI251-3
91	2	-61.023	-55.978	264	CTD/RO	Attention keep 2 nm off mooring
91	3	-61.023	-55.978	264	MOOR/D	Deployment AWI251-4
92	1	-60.119	-57.3267	3879	SOSOCAL	
92	2	-60.119	-57.3267	3879	SOSOCAL	
WP	none	-51.7	-57.8333	1	Stanley	